

# A band-ratio algorithm for retrieving open-lake chlorophyll values from satellite observations of the Great Lakes

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## Abstract

The U.S. Environmental Protection Agency's Great Lakes National Program Office (GLNPO) has collected water quality data from the five Great Lakes annually since 1993. We used the GLNPO observations made since 2002 along with coincident measurements made by the Sea-viewing Wide Field-of-View Sensor (SeaWiFS) and the Moderate-resolution Imaging Spectroradiometer (MODIS) to develop a new band-ratio algorithm for estimating chlorophyll concentrations in the Great Lakes from satellite observations. The new algorithm is based on a third-order polynomial model using the same maximum band ratios employed in the standard NASA algorithms (OC4 for SeaWiFS and OC3M for MODIS). The sensor-specific coefficients for the new algorithm were obtained by fitting the relationship to several hundred matched field and satellite observations. Although there are some seasonal variations in some lakes, the relationship between the observed chlorophyll values and those modeled using the new coefficients is fairly stable from lake to lake and across

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years. The accuracy of the satellite-derived chlorophyll estimates derived from the new algorithm was improved substantially relative both to the standard NASA retrievals and to previously published algorithms tuned to specific lakes. Monte-Carlo fits to randomly selected subsets of the observations allowed us to estimate the uncertainty associated with the retrievals purely as a function of the satellite data. Our results provide, for the first time, a single simple band ratio method for retrieving chlorophyll concentrations in the offshore “open” waters of the Great Lakes from satellite observations.

*Keywords:* Remote sensing, Ocean color, Chlorophyll *a*, Satellite observation

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## 1 **Introduction**

2     The problem of estimating chlorophyll concentration in the surface waters of the Great  
3 Lakes from satellite observations is one that has challenged researchers for years. Al-  
4 though successful chlorophyll retrieval methods have been developed for large areas of  
5 the ocean (Yoder et al., 1993), efforts to develop new or adapt existing algorithms for use  
6 in the Great Lakes have met with, at best, mixed results (Lesht et al., 2012). The ocean  
7 algorithms are based for the most part on an empirical relationship between chlorophyll  
8 concentration and the ratio of the remote sensing reflectance ( $Rrs$ ) measured by the satel-  
9 lite sensor at two wavelengths (bands). When applied to the Great Lakes, the variability  
10 in the performance of these algorithms has been attributed to the presence of confounding  
11 factors such as high concentrations of suspended material (Witter et al., 2009), high con-  
12 centrations of dissolved organic material (Budd and Warrington, 2004), and phytoplankton  
13 populations dominated by particular organisms (Bergmann et al., 2004). The general con-  
14 sensus among workers in this area (Bukata et al., 1985; Mortimer, 1988; Li et al., 2004;  
15 Shuchman et al., 2006; Binding et al., 2008; Lohrenz et al., 2008; Binding et al., 2010) is

16 that simple algorithms based on band ratios are not applicable to the Great Lakes because  
17 the Great Lakes, unlike the open ocean, are assumed to be optically complex “Case 2”  
18 waters (Morel and Prieur, 1977) and the factors that affect the color of the water are not  
19 dominated by phytoplankton pigments.

20 In theory, the influence of optically active non-algal substances, such as non-algal  
21 particulates (NAP, primarily suspended mineral particles), or colored dissolved organic  
22 material (CDOM), that would interfere with the chlorophyll retrievals based on band ratio  
23 methods can be calculated by using models that include the optical effects of these compo-  
24 nents explicitly. These calculations require knowledge of the spectrally resolved scattering  
25 and absorption properties of each optically active component (Preiur and Sathyendranath,  
26 1981). Referred to here as the multi-component method, this approach was first applied  
27 to the Great Lakes by Bukata and colleagues (Bukata et al., 1978, 1979, 1981b,a, 1985,  
28 1991a,b). In the multi-component method the spectral content of the incoming solar radi-  
29 ation reflected from the surface layer of water back to space is modeled as function of the  
30 spectral absorption and backscattering due to the combined effects of the color producing  
31 agents (CPAs, sometimes referred to as optically active constituents or OACs) present in  
32 the water. Attempts that have been made to apply multi-component methods to the Great  
33 Lakes (Bukata et al., 1985; Pozdnyakov et al., 2005; Shuchman et al., 2006) have not  
34 been entirely successful. Bukata et al. (1985) found that when applied to western Lake  
35 Ontario the multi-component method produced estimates that closely matched observed  
36 NAP concentrations and made acceptable estimates of CDOM concentration, but resulted  
37 in substantial underestimation of chlorophyll concentrations. Similarly, when Shuchman  
38 et al. (2006) compared multi-component estimates made from SeaWiFS observations with

39 a limited set (two days) of field measurements of chlorophyll made in the vicinity of the  
40 Kalamazoo River outflow in Lake Michigan the model produced acceptable estimates of  
41 the NAP and CDOM observations, but underestimated the observed chlorophyll concen-  
42 trations by an order of magnitude. More recently, however, Binding et al. (2012) devel-  
43 oped a two-component (phytoplankton and mineral sediment) model for Lake Erie that  
44 is based on the red and near-infrared bands measured by MODIS. This model simulta-  
45 neously estimates the concentrations of suspended mineral particles and chlorophyll and  
46 appears promising when applied to turbid and productive waters. Being based red and  
47 near-infrared wavelengths, this model should be fairly insensitive to the effect of CDOM  
48 absorption which is not included in the model.

49 No matter which components are included, the multi-component methods depend on  
50 the accuracy of the optical cross sections of the CPAs. Although work aimed at provid-  
51 ing new estimates of these cross sections currently is underway (personal communication,  
52 G. Leshkevich, 2011), to the best of our knowledge, those determined by Bukata et al.  
53 (1981b) are the only optical cross sections measured in the Great Lakes that have been  
54 tabulated and published (Bukata et al., 1985). Other detailed optical characterization stud-  
55 ies of the Great Lakes recently have been presented (Lohrenz et al., 2004; Binding et al.,  
56 2008; Effler et al., 2010; O'Donnell et al., 2010; Peng and Effler, 2010; Binding et al.,  
57 2012) but, with the exception of the Binding et al. (2012) study in Lake Erie, they do  
58 not present sufficient information to derive the spectral cross sections needed to apply a  
59 multi-component model. Until multi-component methods are proven and widely avail-  
60 able, we believe that the empirical band ratio approach will provide the primary practical  
61 means of making quantitative estimates of chlorophyll concentrations in the lakes from

62 satellite observations. Of course, because the complicating effects of non-algal substances  
63 can be significant, successful application the band ratio method will be limited to waters  
64 in which the optical properties are dominated by phytoplankton. As we will demonstrate  
65 below, however, waters where the band ratio method is most likely to be compromised  
66 by the presence of confounding substances constitute a small fraction of the Great Lakes  
67 (primarily embayments and shallow waters subject to frequent sediment resuspension).

68 The standard NASA retrieval algorithms are based on the work of O'Reilly et al. (1998)  
69 who conducted an extensive study comparing a large and diverse set of oceanic field mea-  
70 surements of chlorophyll concentrations with predictions made from a number of different  
71 retrieval algorithms. They found that, in general, the multi-component (or semi-analytical)  
72 methods did not perform as well as did band ratio methods. The band ratio methods are  
73 simple to apply and do not require detailed knowledge of the optical cross sections of the  
74 CPAs.

75 The fundamental assumption underlying the empirical band ratio retrieval methods is  
76 that the optical properties of the water are dominated by phytoplankton absorption of in-  
77 coming solar radiation. Because chlorophyll-a absorbs most radiation at shorter (blue)  
78 wavelengths and very little in the middle (green) part of the spectrum (Bricaud and Stram-  
79 ski, 1990; Lohrenz et al., 2004), green light is preferentially reflected by algae. Thus,  
80 the ratio of the blue light reflected from the water (relatively sensitive to concentration of  
81 chlorophyll) to the reflected green light (relatively insensitive to chlorophyll concentration)  
82 should be inversely related to the concentration of phytoplankton in the water. By using  
83 a set of filters tuned to discrete narrow regions (bands) of the electromagnetic spectrum,  
84 satellite sensors like SeaWiFS and MODIS are designed to measure the spectral content

85 of the light reflected from the surface in those bands most appropriate for calculating this  
86 blue/green ratio.

87 The choice of bands used to represent the blue and green portions of the spectrum  
88 varies between sensors and among the several empirical algorithms developed for each  
89 sensor. The current version of the standard NASA band ratio algorithm (see <http://oceancolor.gsfc.nasa.gov/REPROCESSING/R2009/ocv6/>) for SeaWiFS uses the maximum of the  
90 three bands  $\{Rrs_{443}, Rrs_{489}, Rrs_{510}\}$  to represent the blue band and  $Rrs_{555}$  to represent the  
91 green band. For MODIS, the blue band is represented by the maximum of  $\{Rrs_{443}, Rrs_{489}\}$   
92 and the green band by  $Rrs_{547}$ . In both cases, the relationship between chlorophyll ( $Chl_a$ )  
93 and the band ratio is expressed as a fourth-order polynomial in  $X = \log_{10}(Rrs_{blue}/Rrs_{green})$ ,  
94

$$95 \quad \log_{10}(Chl_a) = a_0 + a_1X + a_2X^2 + a_3X^3 + a_4X^4. \quad (1)$$

96 The coefficients used in the standard NASA algorithms were determined by regression  
97 analysis of the large set of coincident *in situ* chlorophyll and *Rrs* measurements obtained  
98 from a wide variety of ocean waters described by O'Reilly et al. (1998). The data set  
99 (SeaBAM) used by NASA in this process is updated periodically and is publicly available  
100 (Werdell et al., 2003). No similar database exists for the Great Lakes, though as noted  
101 above efforts reportedly are underway to develop one (G. Leshkevich, personal communi-  
102 cation, 2011).

103 It is important to understand that the standard NASA chlorophyll retrieval algorithms  
104 were intended to be global in scope. That is, for each sensor, one of the designers' goals  
105 was to develop a single relationship for estimating chlorophyll concentrations regardless  
106 of the time of year or area of the ocean being observed. This goal was achieved by tuning  
107 the candidate algorithms to the SeaBAM data, which were assembled by merging data

108 from a number of different sources (O'Reilly et al., 1998) in which the measured chloro-  
109 phyll concentrations ranged over four orders of magnitude (between 0.019 and 32.79 mg  
110 m<sup>-3</sup>). Of course, because of the large bio-optical diversity in the ocean, it was explic-  
111 itly recognized that no one single algorithm could be optimal in every situation or region.  
112 The expectation, rather, was that the estimates provided by the general algorithm would  
113 provide estimates that were within known and reasonable limits of accuracy.

114 Band ratio estimates of chlorophyll concentration based on the standard NASA algo-  
115 rithms have proven valuable for understanding biological processes in the Great Lakes  
116 (Lesht et al., 2002; Chen et al., 2004; Kerfoot et al., 2008, 2010; Barbiero et al., 2011).  
117 However, other studies have questioned the absolute accuracy of the standard NASA re-  
118 trievals in the Great Lakes (Budd and Warrington, 2004; Li et al., 2004; Bergmann et al.,  
119 2004; Lohrenz et al., 2008; Witter et al., 2009; Watkins, 2009). We noted in our recent  
120 review of the applications of satellite ocean color algorithms to the Great Lakes (Lesht  
121 et al., 2012) that although the slopes, intercepts, and strength of the fits of the linear rela-  
122 tionships between retrieved and observed chlorophyll varied from study to study, retrievals  
123 that were based on the standard NASA band ratio algorithms produced chlorophyll esti-  
124 mates that were linearly related to the concentrations measured in the field, contrary to  
125 expectations based on the assumption that the Great Lakes must be considered Case-2 wa-  
126 ters. Lesht et al. (2012) showed that some variation in the results could be due to variations  
127 in the amounts of the confounding substances present, which undoubtedly differed among  
128 the published studies. Some variation might also to due to the limited extent of the data  
129 used in the underlying studies and/or from procedural differences among them.

130 A few studies have attempted to “tune” or optimize band ratio algorithms for partic-

131 ular regions in the Great Lakes. One common feature of these studies is that they have  
132 been limited to individual lakes. In some cases, this narrow focus stemmed from the re-  
133 searchers' proximity to or interest in the lake in question (Witter et al., 2009; Binding  
134 et al., 2012). In other cases the research was part of a larger program being done in a  
135 specific region (Li et al., 2004). Perhaps because of data limitations or because it has been  
136 assumed that retrieval algorithms must be lake-specific, no previous work has attempted  
137 to derive a single algorithm that would be applicable to all of the lakes. Such an algo-  
138 rithm, similar to the global ocean color algorithms that long have been used in the ocean,  
139 would greatly simplify and enhance efforts to employ satellite data for study of the Great  
140 Lakes. Although it is based on sampling done exclusively in offshore waters, the exten-  
141 sive GLNPO water quality monitoring data can be considered a Great Lakes analogy to  
142 the *in situ* portion of the SeaBAM database used by NASA to develop the global ocean  
143 algorithms. In this paper we describe our use of the GLNPO data to develop of a single  
144 chlorophyll retrieval algorithm for the Great Lakes that is appropriate for those regions of  
145 the lakes that are represented by the GLNPO monitoring program.

## 146 **Methods**

### 147 *Satellite Data*

148 All of the satellite data used in this study were processed with NASA's SeaDAS soft-  
149 ware (Baith et al., 2001), version 6.3. We began with daily SeaWiFS and MODIS L1A im-  
150 agery obtained from NASA's Ocean Color Data archive (<http://oceancolor.gsfc.nasa.gov>).  
151 These image files, which were extracted geographically to limit the imagery to the individ-  
152 ual lakes, included every daytime overpass from shortly after launch (September 1997 for



153 SeaWiFS and July 2002 for MODIS) to the end of the SeaWiFS mission (December 2010)  
154 and through December 2011 for MODIS (which still operates). We used the appropriate  
155 versions of the SeaDAS *l2gen* module to convert the raw L1A raw radiance values to L2  
156 geophysical variable values, adopting the default SeaDAS atmospheric correction scheme  
157 that involves a 2-band model selection with an iterative near infrared (NIR) correction  
158 (Bailey et al., 2010). For days on which two L1A images of a lake were collected we  
159 kept only the image with the more favorable viewing geometry. To avoid computational  
160 artifacts, we did not further resample or grid the L2 files but rather used the original L2  
161 data values in all of our subsequent analyses.

## 162 *Field Observations*

163 Figure 1 shows the locations of the eighty stations sampled regularly by GLNPO be-  
164 tween 1998 and 2011. Surveys were made twice a year, generally in April to monitor  
165 spring conditions and again in August to collect data when the lakes are stratified. The  
166 actual ranges of dates sampled over the years are 11 March through 15 May in the spring  
167 and 30 July through 30 September in the summer. Although we included a two shallow  
168 water stations that were primarily intended to sample benthos in our analysis, the regular  
169 GLNPO monitoring stations were located offshore in the open waters of each lake by de-  
170 sign, and except for those in the shallow western and central basins of Lake Erie, all are  
171 in water that is greater than 30 m deep. All the regular monitoring stations in the central  
172 basin of Lake Erie are in water that is greater than 20 m deep.

173 [Figure 1 here.]

174 At each station, samples for chlorophyll were taken at discrete depths throughout the  
175 entire water column with Niskin bottles mounted on a SeaBird Carousel Water Sampler.

176 For the present study, averages of samples collected from the isothermal upper (10 m)  
177 water column for each station/survey were used. Chlorophyll-a, uncorrected for pheo-  
178 phytin, was determined on a Turner Designs 10-AU fluorometer following the method of  
179 Welschmeyer (1994).

#### 180 *Data Screening and Matching*

181 We matched the field data values to the corresponding pixels in the satellite imagery  
182 as follows: For each field sample we identified the satellite images that were recorded on  
183 or within one day of the date of field collection. Beginning with the image closest in time  
184 to the field sampling, we determined the extent to which the image was contaminated by  
185 cloud cover. The amount of cloud contamination was calculated by dividing the number  
186 of cloudy water pixels by the total number of water pixels. We discarded images that were  
187 more than 80% cloud covered and then checked the next closest image. If none of the im-  
188 ages recorded within a day of the field sample collection passed through this initial screen,  
189 then no match was made for that field observation. For each accepted image we identified  
190 the pixel corresponding to the field location by using geometrical correlation between the  
191 station location and the image pixel locations (see Appendix A for details). We accepted  
192 the observation for analysis only if the all the pixels within a 5x5 pixel box surrounding the  
193 sampling location were cloud free and valid, as indicated by the following SeaDAS data  
194 quality flags: ATMFAIL, LAND, HIGLINT, HILT, STRAYLIGHT, CLDICE, CHLFAIL,  
195 NAVFAIL (<http://oceancolor.gsfc.nasa.gov/VALIDATION/flags.html>).

196 Of the 2126 individual GLNPO samples collected between 1998 and 2011 our match-  
197 ing process resulted in a total of 1035 station/pixel pairs for SeaWiFS (1998-2010) and 974  
198 (2002-2011) for MODIS. We eliminated a number of the matched observations because

one or more of the reflectance values were negative, possibly indicating that the atmospheric correction model overestimated the contributions of scattering aerosols (Bailey et al., 2010). Because Barbiero et al. (2011) found evidence that the GLNPO chlorophyll measurements made prior to 2002 were biased toward low values, we further decided to limit the SeaWiFS data to the period 2002-2010 (the end of the SeaWiFS mission). Our final data set consisted of 454 matches for SeaWiFS and 782 matches for MODIS. The distribution of matched samples/images by lake and year is shown in Table 1. Only three samples (1 for SeaWiFS and 2 for MODIS) came from the shallow benthos stations.

[Table 1 here.]

#### *Model Selection, Fitting, and Evaluation Statistics*

After conducting an extensive analysis of different combinations of band ratios and functional forms, O'Reilly et al. (1998) found that a fourth-order polynomial relating  $\log_{10}(Chl_a)$  to  $X = \log_{10}(Rrs_{blue}/Rrs_{green})$  best represented the SeaBAM data (as noted above,  $Rrs_{blue}$  is  $\max[Rrs_{443}, Rrs_{489}, Rrs_{510}]$  for SeaWiFS and is  $\max[Rrs_{443}, Rrs_{489}]$  for MODIS;  $Rrs_{green}$  is  $Rrs_{555}$  for SeaWiFS and  $Rrs_{547}$  for MODIS). Rather than experiment with different band ratios and functional forms, we chose to use these same ratios and polynomial model in our study, but we found that the Great Lakes data could be represented adequately by a third-order relationship

$$\log_{10}(Chl_a) = a_0 + a_1X + a_2X^2 + a_3X^3. \quad (2)$$

We used the same tuning method described by O'Reilly et al. (1998) to determine the coefficients in Eq. 2. This procedure uses an iterative process in which the model coefficients ( $a_0, a_1, a_2, a_3$  in Eq. 2) are adjusted until the intercept and slope of the linear relationship

221 between  $\log_{10}(Chl_a^{model})$  and  $\log_{10}(Chl_a^{insitu})$  were zero and one respectively. In contrast to  
 222 standard linear regression in which the objective is to determine a set of model coefficients  
 223 that minimizes the sum of the squared differences between the modeled and observed val-  
 224 ues, the iterative method is aimed at determining the set of model coefficients that produces  
 225 a 1:1 relationship between the modeled and observed values. Although the error sum of  
 226 squares may be larger (relative to the standard regression result) when the model coef-  
 227 ficients are determined by using the iterative method, the method facilitates comparison  
 228 between different models by constraining the slope and intercept (O'Reilly et al., 1998;  
 229 Campbell and O'Reilly, 2006).

230 We based our assessment of model performance on statistics calculated from the log-  
 231 transformed data. The log transformation is appropriate (Campbell and O'Reilly, 2006)  
 232 both because the data values vary over several orders of magnitude and because the log  
 233 transformed chlorophyll is more normally distributed than the untransformed data (Fig 2).  
 234 Our evaluation statistics include the slope ( $b$ ) and intercept ( $a$ ) of the best fit regression  
 235 line between the (log transformed) model estimates ( $P_i$ ) and observed values ( $O_i$ ), the  
 236 bias, or the difference between the means of the estimates ( $\bar{P}$ ) and the observations ( $\bar{O}$ )  
 237 (negative bias indicates that the predicted values underestimate the observed values), the  
 238 ratio of the standard deviations of the estimates ( $\sigma_p$ ) and observations ( $\sigma_o$ ), the refined  
 239 index of agreement ( $d_r$ ) (Willmott et al., 2011), the root mean squared error ( $RMS E$ ), the  
 240 percent unsystematic error ( $\%USE$ ) (Willmott, 1982), and the mean absolute error ( $MAE$ )  
 241 (Willmott et al., 2009). For comparison with other studies, we also included the Pearson's  
 242 correlation coefficient ( $r$ ), though this statistic has been shown to be overly sensitive to  
 243 high extreme values (Willmott, 1982; Legates and McCabe, 1999; Moriasi et al., 2007)

244 and is less useful than measures based on the absolute difference between the estimates  
245 and observations (Campbell and O'Reilly, 2006). Because several of these statistics may  
246 be unfamiliar, we provide their formal definitions in Appendix B.

247 [Figure 2 here.]

248 The slope and intercept of the regression line indicate how well the estimates match the  
249 observations. We used a type II (or reduced major axis) model to compute the regression.  
250 This type of model is appropriate when both variables are subject to uncertainty (Press and  
251 Teukolsky, 1992; Press et al., 1992). Bias measures the average tendency of the estimates  
252 to be larger or smaller than the observations; ideally the bias would equal zero. Similarly,  
253 comparing the standard deviations of the estimates and observations shows how well the  
254 model reproduces the overall variation in the data. Both *RMS E* and *MAE* are error indices  
255 that are useful because they characterize the error in the units of the variable of interest.  
256 Because it is based on the squared error, *RMS E* tends to exaggerate large errors and *MAE*  
257 is the preferred statistic (Willmott et al., 2009). In either case, the lower the ratio of  
258 *RMS E* or *MAE* to the standard deviation of the observations, the better the model (Moriassi  
259 et al., 2007). Ideally, models would be free of systematic error (Willmott, 1982). In better  
260 models, the %*USE*, which is the unsystematic proportion of the *RMS E* approaches one.  
261 In addition to evaluating the overall performance of the model, we calculated evaluation  
262 statistics for each lake, for each lake and season, and for each year.

263 The refined index of agreement (Willmott et al., 2011) is a dimensionless statistic,  
264 bounded by  $\pm 1$ , that provides a summary measure of how well the model estimates repro-  
265 duce the data. Based on the absolute values of the difference between the estimates and  
266 observations, this statistic is not overly sensitive to high extreme values. The  $d_r$  statistic

267 is a measure of how well the model (algorithm) predicts the observations relative to how  
 268 well the observations could be predicted by the observed mean. A perfect model, one for  
 269 which  $P_i = O_i$ , would result in a  $d_r$  value of 1. If the sum of the absolute differences  
 270 between the predicted and observed values ( $\sum |O_i - P_i|$ ) is very large relative to the sum of  
 271 the absolute deviations of the observations around their mean ( $\sum |O_i - \bar{O}|$ ) or if there is very  
 272 little observed variability, then  $d_r$  will approach -1. The value of  $d_r$  will be zero when sum  
 273 of the absolute value of the differences between the predictions and observations is twice  
 274 the sum absolute differences of the observations about the observed mean. Models with  
 275  $d_r = 0.5$  result in predictions that are equivalent to using the observed mean as the predic-  
 276 tor and “good” models should have  $d_r$  values  $> 0.5$  indicating that the sum of the absolute  
 277 predicted deviations is less than the sum of the absolute observed deviations. However,  
 278 because characterization of model performance using values of  $d_r$  is somewhat arbitrary  
 279 (Legates and McCabe, 2012), we use the statistic as a relative indicator. When evaluat-  
 280 ing the success of the models applied to our data, we primarily considered the slope, the  
 281 intercept, the *MAE*, and the *%USE*.

## 282 *Estimation of Retrieval and Parameter Uncertainties*

283 We have only one set of matched data for each sensor so we are unable to validate our  
 284 results with a completely independent set of observations. Furthermore, standard methods  
 285 for assessing the uncertainty associated with the model fits are inapplicable to our data  
 286 because the model coefficients were determined by using the iterative method described  
 287 above rather than by using simple least-squares regression. To address these issues we  
 288 adapted a dual Monte Carlo resampling approach (Wei et al., 2008) to estimate the un-  
 289 certainties of our models. In this two step process we first selected (with replacement)

290 a random subset of half the observations. Assuming that both the selected chlorophyll  
291 and maximum band ratio values were samples from independent, normally-distributed,  
292 random variables we then perturbed the observed values by a random error term scaled  
293 to an assumed accuracy for the measured variables (5% for maximum band ratio (Bailey  
294 and Werdell, 2006) and 10% for chlorophyll) and used these perturbed values as the basis  
295 for a new fit. We repeated these random selection processes 1000 times to generate an  
296 ensemble of model coefficients that could be used to estimate confidence intervals for the  
297 predictions as a function of the maximum band ratio. Volpe et al. (2011) used a similar  
298 method to determine confidence intervals for estimates of remote sensing reflectance as a  
299 function of water turbidity.

300 We used a subsampling approach (Hartigan, 1969) to estimate the uncertainty in the  
301 model parameters. Because the number of our matched samples was fairly large, we did  
302 not apply the “leave out one” jackknife analysis adopted by the few other remote sensing  
303 studies that attempted a similar analysis (Volpe et al., 2011; Novoa et al., 2012). Rather,  
304 we partitioned the full data set into halves by years and determined the model coefficients  
305 for each of the five-year partitions. Because the total data set consisted of ten years, there  
306 are 252 unique five-year partitions. We also determined how well the model tuned to each  
307 partition predicted the observations in the complementary partition and used the model  
308 evaluation statistics described above to assess the results.

## Results

### *Satellite images matched with in situ chlorophyll observations*

Chlorophyll concentrations measured by GLNPO between 2002 and 2011 ranged between  $0.19 \text{ mg m}^{-3}$  and  $33.55 \text{ mg m}^{-3}$ , with a geometric mean of  $1.37 \text{ mg m}^{-3}$ . The distribution of the measurements is approximately log-normal, with a slight skew toward larger values. Histograms of the subsets of chlorophyll values that were matched with the SeaWiFS and MODIS observations (Fig. 2) are very similar to overall distribution indicating that the matching process resulted in samples representative of the overall population of observations. The minimum, maximum, and geometric mean of the SeaWiFS-matched chlorophyll values were  $0.24 \text{ mg m}^{-3}$ ,  $24.03 \text{ mg m}^{-3}$ , and  $1.29 \text{ mg m}^{-3}$ . For MODIS, these values were  $0.22 \text{ mg m}^{-3}$ ,  $32.69 \text{ mg m}^{-3}$ , and  $1.30 \text{ mg m}^{-3}$ .

### *Model fit*

Model coefficients derived from GLNPO data (Table 2) resulted in improved fits for both MODIS and SeaWiFS sensors, compared to standard NASA models (Fig. 3). Recalling that the coefficients determined for the Great Lakes Fit (GLF) models (Table 2) were constrained to result in a slope of one and intercept of zero, the values for  $d_r$ , %USE, and MAE were 0.780, 0.976, 0.142 for MODIS and 0.758, 0.956, and 0.158 for SeaWiFS, respectively. For comparison, the slope, intercept, and statistics for the standard NASA models were 0.892, -0.074, 0.761, 0.640, 0.154 for MODIS-OC3M and 0.844, -0.048, 0.739, 0.631, and 0.170 for SeaWiFS-OC4. When based on the entire dataset, the standard NASA relationships tend to underestimate the chlorophyll concentration for both sensors. A larger set of evaluation statistics comparing the GLF model to the standard NASA algorithms is given in Table 3.



332 [Table 2 here.]

333 [Figure 3 here.]

334 [Table 3 here.]

335 Plots (after O'Reilly et al. (1998)) showing the relationships between the observed  
336 chlorophyll values and those predicted using both the standard NASA algorithms and the  
337 GLF model for MODIS and SeaWiFS are shown in Fig. 4. Because the GLF model co-  
338 efficients were determined under the constraint of producing a slope and intercept equal  
339 to one and zero respectively, the relative improvement in the performance of the fitted  
340 models is best illustrated by the changes in the quantile-quantile and frequency distribu-  
341 tion plots. The plots indicate greater deviation between predicted and observed values at  
342 higher chlorophyll concentrations in the standard NASA models (OC3M and OC4) com-  
343 pared to the GLF models. This underestimation of chlorophyll at high concentrations by  
344 the O3M and OC4 models can be seen by the divergence in relative frequencies between  
345 model and *in situ* values at high chlorophyll concentrations Fig. 4. At the most extreme  
346 values, however, all models show notable deviation between observed and predicted val-  
347 ues.

348 [Figure 4 here.]

#### 349 *Fits by lake and by year*

350 The highest chlorophyll concentrations observed in our study come from Lake Erie  
351 where there also seems to be a distinct seasonal bifurcation in the relationship between  
352  $\log_{10}(Chl_a^{in situ})$  and  $\log_{10}$  of the maximum band ratio (MBR), especially for MODIS (Fig. 4  
353 bottom row). This bifurcation is evident when the GLF model is applied separately by  
354 season (Fig. 5 and Table 3). The seasonal difference is most pronounced in Lake Erie

355 (for both MODIS and SeaWiFS), where spring values were underestimated by the model  
356 and summer values were overestimated. The slope of the relationship between the values  
357 predicted by the GLF models and the observations also shows seasonal dependence in both  
358 Lakes Ontario (MODIS and SeaWiFS) and Superior (SeaWiFS).

359 When applied to the individual lakes the MODIS GLF model performs very well (slope  
360 very close to 1, intercept near 0) in Lakes Huron and Michigan (Table 4). The model tends  
361 to under-predict the observations made in Lakes Erie and Superior, though the slopes are  
362 still greater than 0.92. In Lake Ontario, the slope is higher than would be expected (1.45),  
363 but this determination is based on considerably fewer samples than in the other lakes.  
364 The SeaWiFS GLF results are similar for Lakes Erie, Huron, Michigan, and Ontario with  
365 slopes between 0.91 and 1.16. The Lake Superior slope is somewhat higher (1.25). In both  
366 cases with high slopes (MODIS Ontario and SeaWiFS Superior) the standard deviation of  
367 the model predictions is higher than the standard deviation of the observations, suggest-  
368 ing the presence of some outlier observations. We did not attempt to identify or remove  
369 possible outliers in this analysis.

370 [Figure 5 here.]

371 [Table 4 here.]

372 When the GLF model is applied to all lakes by year the quality of the predictions are  
373 remarkably stable (Table 5). For MODIS the slope of the relationship between the values  
374 predicted by the GLF and the observations varies between 0.911 (2007) and 1.150 (2005)  
375 and *MAE* between 0.108 (2010) and 0.179 (2011). For SeaWiFS the slope varies between  
376 0.940 (2007) and 1.417 (2010) and *MAE* between 0.129 (2003) and 0.186 (2006). We  
377 note, however, that the SeaWiFS sensor experienced problems throughout 2010 before

378 failing completely in December of that year so the results for 2010 may be suspect.

379 [Table 5 here.]

### 380 *Comparison with published regionalized models*

381 Only a few studies have been published in which researchers attempted to improve  
382 the local accuracy of chlorophyll retrievals by fitting new band ratio models to data col-  
383 lected in the Great Lakes. Li et al. (2004) (L-2004) used *in situ* optical measurements and  
384 least squares methods to optimize the fit of the OC4 algorithm (Eq. 1) to chlorophyll data  
385 they collected in Lake Superior. The set of optimized coefficients are given as {0.3815,  
386 -1.6837, 2.5054, -0.5899, -0.6505} (L-2004, page 452). When applied to our data, the  
387 results (Fig. 6, bottom panel) show that a 4th order model with these coefficients blows up  
388 at higher values of the maximum band ratio and predicts unrealistically low chlorophyll  
389 concentrations (relative to the GLNPO chlorophyll observations). This problem is avoided  
390 in the 3rd order GLF model (Fig. 6, top panel) which produces reasonable predictions (in-  
391 tercept = 0.032, slope = 1.247, MAE = 0.121) over the narrow range of chlorophyll values  
392 (0.5 mg m<sup>-3</sup> to 1.9 mg m<sup>-3</sup>) that were observed in Lake Superior.

393 [Figure 6 here.]

394 Witter et al. (2009) (W-2009) used data collected in Lake Erie to develop a set of  
395 “regional algorithms” that were tuned both for whole lake and for the three individual  
396 lake basins. Rather than use an algorithm in the same form as Eq. 1, W-2009 found  
397 that the expression  $Chl_a = 10^{a+bR+cR^2}$ , where  $R = \log(Rrs_{490}/Rrs_{555})$  and  $a, b$ , and  $c$  are  
398 a set of coefficients specific to the whole lake, and western, central, and eastern basins,  
399 resulted in a statistically improved relationship (relative to estimates from the standard  
400 NASA algorithms) between the calculated and observed chlorophyll values, though the

401 tuned estimates still tended to underestimate the observed values. When we applied the  
402 W-2009 models to our data (Fig. 7, first column), we found that although the slope of  
403 the fit for the whole-lake was close to one, the model was biased low (observed values  
404 were higher than the modeled values). Seasonal differences in the relationship between  
405 the modeled and observed chlorophyll are seen in both the GLF and W-2009 models with  
406 the apparent slope for the spring data being lower than that for the summer data. Although  
407 it is not basin-specific, the GLF model produced estimates in the eastern and central basins  
408 with MAE values of 0.180 and 0.186 (log units) respectively. The overall (not seasonally  
409 separated) GLF predictions in the more turbid and productive western basin had an MAE  
410 of 0.322. The MAE values for the W-2009 model were 0.305, 0.422, and 0.343 in the  
411 eastern, central, and western basins respectively. The GLF tended to over predict the  
412 lower range of chlorophyll values observed in the spring in all basins. The over prediction  
413 was largest in the western basin.

414 [Figure 7 here.]

415 The Binding et al. (2012) model (B-2012) uses the multi-component approach to si-  
416 multaneously estimate the concentrations of suspended mineral particles and chlorophyll  
417 in Lake Erie from MODIS data. Overall, we found that this multicomponent model did not  
418 perform as well as did the GLF when compared to the GLNPO observations (Fig. 8). The  
419 intercept, slope, and MAE values for the GLF model were 0.087, 0.917, and 0.209 com-  
420 pared to -0.318, 1.226, and 0.382 for B-2012. The B-2012 model, however, was developed  
421 primarily for application to turbid and productive waters and can result in artificially low  
422 concentration values (sometimes negative estimates) in clearer waters. As is the case for  
423 the GLF model, there seems to be some seasonal dependence in the B-2012 predictions,

424 with the slope of the relationship between the modeled and observed chlorophyll values  
425 lower in the spring than in the summer at higher chlorophyll values ( $> 4 \text{ mg m}^{-3}$ ) where  
426 the B-2012 model should be most accurate.

427 [Figure 8 here.]

#### 428 *Parameter and prediction uncertainty*

429 The distributions of the model parameters determined from the 252 unique five-year  
430 partitions show that for all the parameters the mean values of the distributions are very  
431 close to the values obtained by fitting to the entire dataset (Fig. 9). Performance of the  
432 models fit to the complementary five-year partitions is comparable to the performance  
433 of overall model. The mean value of  $d_r$  for the partitioned subsets is 0.772 for MODIS  
434 and 0.743 for SeaWiFS with ranges of [0.736, 0.798] and [0.674, 0.791] respectively,  
435 suggesting that the model calibration is robust. A complete listing of the fit statistics for  
436 the independent data sets is given in Table 6.

437 [Figure 9 here.]

438 [Table 6 here.]

439 The estimated chlorophyll prediction error is shown as a function of the observed max-  
440 imum band ratio in Fig. 10. By enumerating the Monte Carlo generated values in a number  
441 of bins along the MBR axis, we were able to estimate empirical confidence intervals for the  
442 model predictions (the 80% interval is listed in Table 7 along with the  $\pm 1\sigma$  interval). For  
443 both MODIS and SeaWiFS, the GLF predictions become very uncertain when  $\log_{10}(\text{MBR})$   
444 values are very low, ( $< -0.3$  for MODIS,  $< -0.2$  for SeaWiFS). In our data, however, ob-  
445 servations in this range are fairly rare (Fig. 11). Throughout most of the range of observed  
446 MBR values, the estimated accuracy of the retrieved chlorophyll concentrations is better

447 than 30%.

448 [Figure 10 here.]

449 [Table 7 here.]

450 Figure 11 here.]

## 451 **Discussion**

452 The GLF models presented here represent the first chlorophyll retrieval algorithms  
453 tuned to data from all five Laurentian Great Lakes. Our study is unique in both its  
454 spatial and temporal extent, covering all five lakes and including ten years of data and  
455 our results clearly demonstrate a consistent relationship between satellite-measured blue-  
456 green reflectance ratios and surface chlorophyll concentrations in the offshore waters of  
457 the Great Lakes represented by the GLNPO monitoring program. Based on several ap-  
458 propriate statistical measures, including the slope and intercept of the linear relationship  
459 between the modeled and observed log-transformed chlorophyll concentrations, the mean  
460 absolute error, and the revised index of agreement, the GLF model outperformed both the  
461 standard ocean-derived algorithms (OC4 for SeaWiFS and OC3M for MODIS, O'Reilly  
462 et al. (1998)) as well as regionally-tuned, lake-specific, algorithms developed for Lake  
463 Erie (Witter et al., 2009; Binding et al., 2012) and Lake Superior (Li et al., 2004).

464 Based on our Monte-Carlo simulations, we estimate that the accuracy of the GLF pre-  
465 dictions throughout most of the expected concentration range in the offshore waters of  
466 the Great Lakes is better than the  $\pm 35\%$  criterion established for the standard NASA algo-  
467 rithms for Case 1 ocean waters (McClain et al., 1992). We note that the errors in reflectance  
468 and chlorophyll assumed above are intended to represent random measurement variability

469 and not the systematic variability that would result from the contributions of non-algal  
470 substances to the radiance values. This latter (and likely larger) source of variability is  
471 represented by the random selection of samples. For example, if the set of selected obser-  
472 vations includes samples in which non-algal substances dominate the reflectance spectrum  
473 (and band ratio), then the resulting variability should be reflected in the predicted chloro-  
474 phyll concentrations. Of course, the degree to which this latter source of variability is  
475 included in our data depends on the extent to which interfering substances influenced the  
476 input observations. Because the GLNPO data were primarily collected in offshore wa-  
477 ters where the effects of interferences would tend to be minimal, our estimates will likely  
478 underestimate the uncertainty that might be associated with observations made near the  
479 shore, in very turbid waters, or waters with high concentrations of CDOM.

480 The GLF is based on a third-order polynomial (Eq. 2) rather than on the fourth-order  
481 polynomial used in the NASA OC3M and OC4 algorithms (Eq. 1). O'Reilly et al. (1998)  
482 note that adding the higher order (fourth) term in their relationship served to improve the  
483 fit at the lowest chlorophyll values. Because the lowest chlorophyll concentration observed  
484 in the Great Lakes is an order of magnitude larger than the lowest value in the ocean data  
485 set ( $0.19 \text{ mg m}^{-3}$  in the Great Lakes versus  $0.019 \text{ mg m}^{-3}$  in SeaBAM) and the highest  
486 chlorophyll concentrations are comparable ( $33.55 \text{ mg m}^{-3}$  in the lakes data versus  $32.79$   
487  $\text{mg m}^{-3}$  in the ocean) the extra term is unnecessary for modeling the Great Lakes. The  
488 retrievals based on the NASA algorithms are biased low throughout the entire range of  
489 observed chlorophyll concentrations but the greatest differences between the NASA re-  
490 trievals and those obtained using the GLF occur at higher concentrations. This difference  
491 may represent a compositional distinction between the coastal ocean samples that con-

492 tribute to the higher chlorophyll concentrations in the SeaBAM data and those (primarily  
493 Lake Erie) samples that contribute the high chlorophyll values in the GLNPO data.

494 Because the Lake Erie samples appear to drive the major differences between the  
495 NASA and GLF results, we repeated the GLF analysis on the data base eliminating the  
496 Lake Erie samples. As would be expected the reduced-set (without Lake Erie) GLF model  
497 coefficients differ from those derived using the entire data set. The new  $a_0$ ,  $a_1$ ,  $a_2$ , and  $a_3$   
498 values for MODIS are {0.3269, -2.7992, 1.2031, and 1.9369}. For SeaWiFS the coefficient  
499 set is {0.3889, -2.6479, 0.4819, -1.1660}. As measured by the change in slope, intercept,  
500  $d_r$ ,  $MAE$ , and  $\%MAE$ , the overall GLF fit to the remaining lakes was improved only  
501 marginally. On the other hand, the ability of the NASA algorithms to model the GLNPO  
502 observations was much improved, with slopes much closer to one (1.013 for MODIS,  
503 0.964 for SeaWiFS). The NASA algorithms, however, still had much higher bias than the  
504 GLF fits (0.072 for MODIS and 0.028 for SeaWiFS).

505 Although some samples were obtained in coastal waters the SeaBAM dataset was  
506 drawn primarily from Case 1 non-polar waters in which optical properties are dominated  
507 by phytoplankton and their associated products (O'Reilly et al., 1998). The coefficients  
508 for the standard OC3M and OC4 equations were derived from SeaBAM and thus, these  
509 coefficients would not be expected to perform well in more optically complex Case-2 wa-  
510 ters in which non-algal derived substances, such as mineral suspended solids and colored  
511 dissolved organic matter, significantly influence optical properties. Our results show that  
512 a band ratio model can be used successfully in the offshore areas of the Great Lakes. This  
513 fact implies that, at least on a statistical basis, these waters are similar to the ocean Case 1  
514 waters in which the optical properties are dominated by phytoplankton.



515 Many studies, however, have shown that the standard band ratio equation form can  
516 still be appropriate for optically complex waters when fitted to a regional dataset. For  
517 example, McKee et al. (2007) derived sets of OC4 coefficients for two optical water types  
518 a study assessing the applicability of blue/green reflectance ratios to estimate chlorophyll  
519 in the Irish and Celtic Seas. The resulting models performed well, indicating that the  
520 standard multiple band ratio equation form can be appropriate for shelf seas. Werdell  
521 et al. (2007) successfully developed a tuned OC3 type algorithm for estimating chlorophyll  
522 concentrations in Chesapeake Bay. A regionally-tuned version of OC4 also improved  
523 the accuracy of SeaWiFS retrievals in the Yellow and East China Seas (Siswanto et al.,  
524 2011), although an alternative equation form (Tassan, 1994) proved superior at high TSM  
525 concentrations. In the Baltic Sea, however, developed tuned standard algorithms for both  
526 MODIS and SeaWiFS substantially reduced bias in chlorophyll retrievals, but were still  
527 deemed unsatisfactory in view of large associated RSME (Darecki and Stramski, 2004).

528 None of the few previous instances where band ratio model tuning has been attempted  
529 in the Great Lakes has resulted in accurate retrievals. In W-2009 the tuned models pro-  
530 vided better estimates than did the standard NASA models but the tuned estimates still  
531 were lower than the observations. Li et al. (2004) (L-2004) however, were unable to find  
532 a tuned model that was significantly better than the NASA algorithm. When applied to  
533 our observations, the W-2009 basin-specific models (Witter et al., 2009) generally under-  
534 predicted the *in situ* data. As mentioned above, Barbiero et al. (2011) found evidence that  
535 the GLNPO chlorophyll measurements made prior to 2002 were likely too low. Because  
536 most of the data used by W-2009 to calibrate their model were obtained from GLNPO  
537 surveys made between 1998 and 2002 this low bias might account for under-prediction

538 of W-2009. The negative bias in the tuned W-2009 model is also seen in the results  
539 for the individual basins. Li et al. (2004) suggest that the low ratio of chlorophyll-*a* to  
540 CDOM precludes the use of empirical approaches in Lake Superior. However, this con-  
541 clusion is based on the poor performance of L-2004 model in the coastal waters sampled  
542 by L-2004 where CDOM concentrations may be high due to riverine inputs. As might  
543 be expected, the L-2004 also fails when applied to our observations, which come entirely  
544 from offshore regions where the GLF model provides reasonably good predictions in Lake  
545 Superior (Fig. 6).

546 The tendency of both the MODIS and SeaWiFS GLFs to underestimate the observed  
547 chlorophyll in Lakes Erie and Ontario (Fig. 5) in the spring and to overestimate chlorophyll  
548 in the summer may be due to seasonal differences in the phytoplankton population. Spe-  
549 cific absorption coefficients of phytoplankton can vary due to differences in pigment com-  
550 position, cell size and amount and distribution of pigment within the cell, (e.g., Sathyen-  
551 dranath et al. (1987)). As a result, phytoplankton community composition will impact es-  
552 timation of chlorophyll from ocean-color data (Carder et al., 1999; Sathyendranath et al.,  
553 2001). For instance, Stuart et al. (2000) have shown that diatom populations exhibit lower  
554 specific absorption coefficients, relative to prymnesiophytes, in the Labrador Sea due to  
555 increased pigment packaging and increased intra-cellular chlorophyll *a*, while Bergmann  
556 et al. (2004) have hypothesized that the accuracy of blue/green reflectance ratios in the  
557 Great Lakes can be compromised by phycobilin-containing algae. Sathyendranath et al.  
558 (2004) used a model to estimate the effects of changes in the dominance of diatoms on  
559 the reflectance ratio and found that, for equal values of chlorophyll concentration, diatom-  
560 dominated populations would tend to have higher reflectance ratios than populations of

561 mixed phytoplankton. Therefore, dominance of phytoplankton communities by larger di-  
562 atoms might lead to underestimation of retrieved chlorophyll. While the differences in the  
563 calculated ratios by Sathyendranath et al. (2004) were relatively small ( $\sim 5\%$ ), the effect on  
564 concentration estimates would be amplified at low band ratio (high concentration) values  
565 because of the polynomial form of the retrieval models. Spring phytoplankton commu-  
566 nity composition in Lake Erie, particularly in the central and eastern basins, is notable for  
567 being dominated by the large-celled diatom *Aulacoseira islandica* (GLNPO, unpublished  
568 data). Because the GLF coefficients were tuned to the complete dataset, the GLF estimates  
569 will generally fall between the extremes defined by pure diatom and mixed plankton pop-  
570 ulations in more productive regions of the lakes. The relatively wide confidence intervals  
571 associated with low band ratio values (Fig. 10) reflect the effect of this seasonal bifurca-  
572 tion. Seasonal differences in the fit are much less pronounced in the other lakes because  
573 chlorophyll values are generally low (higher band ratio values).

574 In addition to differences due to changes in the phytoplankton populations, chlorophyll  
575 overestimates in Lake Ontario during the summer may also result from whiting events  
576 (Peng and Effler, 2010) that cause high reflectance values in the green portion of the spec-  
577 trum (Wortman, 2005). High green reflectance values would tend to reduce the observed  
578 band ratio and result in higher estimated chlorophyll values. GLNPO summer sampling  
579 during the years 2005, 2006, and 2007 coincided with peaks in satellite observed values  
580 of  $Rrs_{555}$  (J. Watkins, personal communication, 2012) and these three years accounted  
581 for almost half of the total number of matched samples from Lake Ontario in our data  
582 (Table 1).

583 No previous study of chlorophyll retrievals done in the Great Lakes has used such an

extensive set of data, nor has one attempted to provide any characterization of the uncertainty associated with the estimates. Although it is likely that random variations in the quantities of interfering substances contribute most to the uncertainty associated with the GLF retrievals, other factors that are difficult to ignore also may have some affect. Among these are errors in the basic measurements of chlorophyll and reflectance (including inaccuracy in the atmospheric correction algorithm embedded in the radiometric calibrations) and temporal and spatial differences in the matching of the *in situ* and satellite observations. Our Monte-Carlo approach was intended to simulate the combined effects of these error sources. The question of uncertainty becomes most important when satellite data are used to estimate absolute values of chlorophyll and to assess the significance of apparent changes in concentration in space or over time. For example, using SeaWiFS data Barbiero et al. (2011) found that spring chlorophyll levels in Lake Huron declined by approximately 50% between 1998-2002 and 2003-2006. The SeaWiFS estimated average Lake Huron southern basin spring (April-May) chlorophyll concentration in 2003-2006 was  $\sim 1.0 \text{ mg m}^{-3}$ , a decline of approximately  $0.8 \text{ mg m}^{-3}$  from the values estimated for the 1998-2002 period. Based on the empirical confidence limits shown in Table 7, a change of this magnitude is unlikely ( $<10\%$ ) to be an artifact of the retrieval uncertainty.

## Conclusion

Algorithms based on the blue-green band ratio are among the most simple of the methods designed to retrieve surface water chlorophyll concentration from satellite observations. The practical utility of the band ratio method results from this simplicity. Estimates of blue and green reflectance from satellite sensors are readily available and the compu-

606 tation required to convert reflectance values into estimates of chlorophyll concentration is  
607 straightforward and easily implemented. By using a single set of sensor-dependent co-  
608 efficients, the GLF model makes it possible to make consistent estimates of chlorophyll  
609 concentration across the lakes without the necessity of adjusting coefficients on the basis  
610 of location, season, or year.

611 Discovering the limits of band ratio methods applied to the Great Lakes is an ongoing  
612 process. We expect our results to be most applicable to the offshore waters represented  
613 by the GLNPO monitoring program. The regular GLNPO monitoring program does not  
614 include sampling in the major Great Lakes embayments such as Green Bay, Saginaw Bay,  
615 the North Channel, Georgian Bay, and the Bay of Quinte. Because these areas are out-  
616 side the our sampling universe, we would not necessarily expect that our results would be  
617 applicable to satellite observations of these waters, nor would we necessarily expect our  
618 results to be applicable to shallow or nearshore waters strongly influenced by sediment  
619 resuspension or the presence of high concentrations of CDOM. Some work has been re-  
620 ported in which satellite observations have been used to determine if waters are Class-1 or  
621 Class-2 (Lee and Hu, 2006; Matsushita et al., 2012) and to classify inland waters before  
622 choosing a retrieval algorithm that has been tuned to water type (Le et al., 2011; Li et al.,  
623 2012). Such methods may be applicable to the Great Lakes and we are exploring that  
624 possibility using the GLNPO data.

625 Further work is needed to determine the causes of the apparent seasonal bifurcation  
626 in the relationship between observed chlorophyll and the maximum band ratio at higher  
627 chlorophyll concentrations and to understand how errors in the retrievals might be related  
628 to other properties of the surface water that are observable by satellite. Validation of the

629 GLF model with independent data also is very desirable. Although the GLF performs  
630 well, other algorithmic approaches also should be explored. Given the appropriate opti-  
631 cal cross-sections, the two-component model developed for Lake Erie by Binding et al.  
632 (2012) based on two bands in the red and near-infrared is fairly simple to apply and shows  
633 promise for providing simultaneous estimates of both chlorophyll and suspended mineral  
634 concentrations in productive regions of the lakes. Similarly, the five-band algorithm devel-  
635 oped by Gohin et al. (2002) that incorporates both the blue-green ratio as well as radiances  
636 at two other wavelengths was successful when applied to the coastal Bay of Biscay (Gohin  
637 et al., 2005), the English Channel (Gohin et al., 2002), and the Bay of Bengal and Arabian  
638 Sea (Tilstone et al., 2011) and should be investigated using data from the Great Lakes.

639 A simple band ratio method using a single set of sensor-specific coefficients can pro-  
640 vide consistent estimates of chlorophyll concentrations in the offshore surface waters of  
641 Great Lakes with accuracy comparable to that required for oceanic estimates. The uncer-  
642 tainty associated with the chlorophyll retrievals also can be estimated from the satellite  
643 data making it possible to assign confidence limits to the estimates. Because the model is  
644 independent of lake and time, application of the GLF to satellite images of the Great Lakes  
645 provides the means for quantitative analysis of differences within and between lakes and  
646 over time. Applying the GLF to both historical and contemporary satellite observations  
647 should greatly facilitate use of this imagery in studies of phytoplankton processes in the  
648 Great Lakes.

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# 654 Appendices

## 655 A. Matching station locations with image pixels

656 We let  $plat, plon$  represent the latitude and longitude of the image pixels and  $flat, flon$   
657 the latitude and longitude of the field station. To determined the image pixel corresponding  
658 to the field location we let

$$uvp[0] = \cos(plat) * \cos(plon)$$

$$uvp[1] = \cos(plat) * \sin(plon)$$

$$uvp[2] = \sin(plat)$$

659 and

$$uvf[0] = \cos(flat) * \cos(flou)$$

$$uvf[1] = \cos(flat) * \sin(flou)$$

$$uvf[2] = \sin(lat)$$

and then calculate the dot product between the  $uvp$  and  $uvf$  vectors,

$$dot = uvp[0] * uvf[0] + uvp[1] * uvf[1] + uvp[2] * uvf[2].$$

Finding the maximum value of the dot product yields the location of the desired image pixel. Once this pixel was located, we checked to ensure that it and all pixels within a 5-km radius of it were cloud free and had valid data (as determined by the status of the L2 data quality flags). Only if these criteria were met did we accept the station and image pair for further analysis

## B. Model comparison statistics

Following Willmott (1982) and Willmott et al. (2011), given a set of  $N$  paired observations,  $O_i$  and model predictions,  $P_i$  we define the following statistics that appear in the text. Following Campbell and O'Reilly (2006) these statistics are based on the log-transformed variables.

$$\bar{O} = N^{-1} \sum_{i=1}^N O_i, \text{ the mean of the observations.}$$

$$\bar{P} = N^{-1} \sum_{i=1}^N P_i, \text{ the mean of the predicted values.}$$

$\hat{P}_i = a + bO_i$ , the linear fit prediction of  $P_i$ , where  $a$  and  $b$  are the intercept and slope of the least-squares regression of  $P$  on  $O$ .



681

682  $MS E_s = N^{-1} \sum_{i=1}^N (\hat{P}_i - O_i)^2$ , the systematic error of the model.

683

684  $MS E_u = N^{-1} \sum_{i=1}^N (P_i - \hat{P}_i)^2$ , the unsystematic error of the model.

685

686  $MSE = MS E_s + MS E_u$ , the mean square error.

687

688  $\%USE = MS E_u / MSE$ , the percent unsystematic error.

689

690  $RMSE = [N^{-1} \sum_{i=1}^N (P_i - O_i)^2]^{0.5}$ , the root mean square error.

691

692  $MAE = N^{-1} \sum_{i=1}^N |P_i - O_i|$ , the mean absolute error.

693

694 The revised index of agreement ( $d_r$ ),

695

$$d_r = \begin{cases} 1 - \frac{\sum_{i=1}^n |P_i - O_i|}{2 \sum_{i=1}^n |O_i - \bar{O}|}, & \text{when} \\ \sum_{i=1}^n |P_i - O_i| \leq 2 \sum_{i=1}^n |O_i - \bar{O}| \\ \frac{2 \sum_{i=1}^n |O_i - \bar{O}|}{\sum_{i=1}^n |P_i - O_i|} - 1, & \text{when} \\ \sum_{i=1}^n |P_i - O_i| > 2 \sum_{i=1}^n |O_i - \bar{O}| \end{cases}$$

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MODIS	Lake					
Year	Erie	Huron	Michigan	Ontario	Superior	Total
2002	12	7	0	4	8	31
2003	32	11	16	1	21	81
2004	28	12	6	6	20	72
2005	23	18	21	15	21	98
2006	28	6	16	15	22	87
2007	18	12	9	12	22	73
2008	29	25	12	5	28	99
2009	22	21	11	13	16	83
2010	11	11	10	9	26	60
2011	30	20	3	11	34	98
Total	233	143	104	84	218	
SeaWiFS						
Year	Erie	Huron	Michigan	Ontario	Superior	Total
2002	29	3	12	7	8	59
2003	24	10	13	1	4	52
2004	23	9	13	4	5	54
2005	23	14	14	12	9	72
2006	35	13	12	2	8	70
2007	17	7	13	12	8	57
2008	5	9	1	0	3	18
2009	18	11	6	5	0	40
2010	1	6	7	2	16	32
Total	175	82	91	45	61	

Table 1: Number of Matched Field/Satellite Samples

Sensor	$a_0$	$a_1$	$a_2$	$a_3$
MODIS	0.3429	-3.3925	3.3412	0.7857
SeaWiFS	0.4006	-4.0975	10.6576	-16.4647

Table 2: Coefficients of the GLF model ( $\log_{10}(Chl_a^{mod}) = a_0 + a_1*X + a_2*X^2 + a_3*X^3$ ) for MODIS and SeaWiFS.  $X = \log_{10}$  of the maximum band ratio (MBR).

Model	Intercept	Slope	$r$	Bias	$\sigma_{pred}/\sigma_{obs}$	$d_r$	RMSE	%USE	MAE	N
All data										
OC3M	-0.074	0.892	0.891	0.090	0.893	0.761	0.203	0.640	0.154	782
MOD3-GLF	-0.000	1.040	0.891	-0.006	1.041	0.780	0.191	0.976	0.142	782
OC4	-0.048	0.844	0.841	0.078	0.845	0.739	0.229	0.631	0.170	454
SWF4-GLF	0.001	1.052	0.834	-0.012	1.053	0.758	0.237	0.956	0.158	454
Spring data										
OC3M	-0.060	0.742	0.893	0.106	0.742	0.756	0.231	0.391	0.172	408
MOD3-GLF	0.006	0.875	0.899	0.016	0.876	0.798	0.191	0.759	0.143	408
OC4	-0.013	0.789	0.797	0.065	0.789	0.719	0.266	0.586	0.200	252
SWF4-GLF	0.038	1.023	0.791	-0.044	1.022	0.736	0.283	0.892	0.188	252
Summer data										
OC3M	-0.085	1.094	0.924	0.073	1.094	0.771	0.167	0.808	0.135	374
MOD3-GLF	-0.002	1.263	0.917	-0.029	1.264	0.760	0.192	0.889	0.141	374
OC4	-0.083	0.913	0.911	0.095	0.913	0.776	0.173	0.582	0.133	202
SWF4-GLF	-0.038	1.067	0.906	0.029	1.067	0.797	0.161	0.963	0.121	202

Table 3: Statistics of NASA and GLF models fit to data [ $\log_{10}(Chl_a^{mod})$  vs.  $\log_{10}(Chl_a^{insitu})$ ] with seasonal subsets (see Methods for explanation of abbreviations in column headings).



Lake	Intercept	Slope	$r$	Bias	$\sigma_{pred}/\sigma_{obs}$	$d_r$	RMSE	%USE	MAE	N
MODIS										
Erie	0.087	0.917	0.675	-0.037	0.917	0.624	0.268	0.745	0.209	233
Huron	-0.005	1.010	0.723	0.007	1.011	0.640	0.117	0.868	0.091	143
Michigan	-0.063	0.999	0.767	0.063	0.999	0.608	0.128	0.670	0.105	104
Ontario	-0.118	1.448	0.601	-0.023	1.447	0.415	0.214	0.976	0.181	84
Superior	-0.007	0.938	0.390	0.002	0.938	0.472	0.143	0.649	0.108	218
SeaWiFS										
Erie	0.110	0.906	0.639	-0.059	0.906	0.619	0.302	0.704	0.215	175
Huron	0.037	1.165	0.729	-0.010	1.166	0.613	0.139	0.961	0.102	82
Michigan	-0.068	0.937	0.724	0.066	0.937	0.603	0.134	0.609	0.109	91
Ontario	-0.087	1.030	0.662	0.077	1.031	0.576	0.190	0.714	0.138	45
Superior	0.032	1.247	0.466	-0.016	1.246	0.430	0.154	0.864	0.121	59

Table 4: Statistics of GLF model fit to data [ $\log_{10}(Chl_a^{mod})$  vs.  $\log_{10}(Chl_a^{insitu})$ ] for all years by lake (see Methods for explanation of abbreviations in column headings).

Year	Intercept	Slope	$r$	Bias	$\sigma_{pred}/\sigma_{obs}$	$d_r$	RMSE	%USE	MAE	N
MODIS										
2003	-0.008	0.948	0.921	0.019	0.948	0.817	0.157	0.881	0.124	81
2004	0.021	1.116	0.854	-0.036	1.117	0.740	0.169	0.947	0.116	72
2005	-0.028	1.150	0.887	-0.000	1.150	0.750	0.220	0.999	0.149	98
2006	0.045	1.109	0.916	-0.059	1.109	0.779	0.176	0.886	0.139	87
2007	-0.056	0.911	0.884	0.070	0.911	0.764	0.216	0.739	0.166	73
2008	0.022	0.914	0.895	-0.015	0.914	0.805	0.204	0.829	0.151	99
2009	-0.029	0.964	0.885	0.035	0.964	0.778	0.179	0.870	0.136	83
2010	-0.049	1.131	0.914	0.042	1.132	0.734	0.135	0.898	0.108	60
2011	0.017	1.107	0.907	-0.037	1.107	0.785	0.230	0.974	0.179	98
SeaWiFS										
2002	0.093	1.039	0.761	-0.099	1.039	0.685	0.252	0.771	0.176	59
2003	-0.046	0.970	0.916	0.056	0.970	0.803	0.164	0.819	0.129	52
2004	0.004	1.012	0.812	-0.006	1.011	0.744	0.201	0.915	0.136	54
2005	-0.079	1.113	0.881	0.052	1.114	0.738	0.226	0.947	0.161	72
2006	0.082	1.169	0.842	-0.114	1.170	0.756	0.298	0.853	0.186	70
2007	-0.041	0.940	0.808	0.055	0.939	0.769	0.288	0.809	0.180	57
2008	0.064	1.324	0.922	-0.086	1.325	0.790	0.220	0.712	0.130	18
2009	-0.033	0.954	0.900	0.045	0.954	0.822	0.200	0.851	0.140	40
2010	0.050	1.417	0.586	-0.034	1.418	0.307	0.179	0.943	0.144	32

Table 5: Statistics of GLF model fit to data [ $\log_{10}(Chl_a^{mod})$  vs.  $\log_{10}(Chl_a^{insitu})$ ] from all lakes by year. MODIS began producing data after the GLNPO sampling was completed in 2002 (see Methods for explanation of abbreviations in column headings).

Statistic	Mean	$\sigma$	Minimum	Maximum
MODIS				
Intercept	-0.001	0.023	-0.061	0.063
Slope	1.057	0.089	0.878	1.348
$r$	0.888	0.009	0.831	0.906
Bias	0.008	0.029	-0.066	0.081
$d_r$	0.772	0.013	0.736	0.798
RMSE	0.200	0.023	0.163	0.324
%USE	0.937	0.053	0.724	1.000
MAE	0.146	0.010	0.124	0.182
SeaWiFS				
Intercept	0.002	0.046	-0.096	0.112
Slope	1.062	0.102	0.864	1.342
$r$	0.695	0.033	0.605	0.786
Bias	0.013	0.057	-0.126	0.142
$d_r$	0.743	0.020	0.674	0.791
RMSE	0.247	0.028	0.186	0.319
%USE	0.889	0.082	0.572	1.000
MAE	0.167	0.012	0.137	0.199

Table 6: Statistics of  $\log_{10}(Chl_a^{mod})$  vs.  $\log_{10}(Chl_a^{insitu})$  for five-year partitioned model fits. Coefficients calibrated with five-year partitions were used to model the observed chlorophyll in the complementary partitions (see Methods for explanation of abbreviations in row labels).

$\overline{\log_{10}(MBR)}$	$\overline{\log_{10}(Chl_a^{mod})}$	$Chl_a^{mod} - \sigma$ (mg/m <sup>3</sup> )	$Chl_a^{mod}$ (mg/m <sup>3</sup> )	$Chl_a^{mod} + \sigma$ (mg/m <sup>3</sup> )	10% quantile (mg/m <sup>3</sup> )	90% quantile (mg/m <sup>3</sup> )
MODIS						
0.349	-0.383	0.381	0.414	0.449	0.371	0.456
0.249	-0.280	0.472	0.525	0.584	0.457	0.609
0.149	-0.087	0.698	0.819	0.960	0.663	1.022
0.050	0.184	1.239	1.527	1.882	1.156	2.039
-0.050	0.522	2.599	3.330	4.267	2.385	4.677
-0.150	0.913	6.050	8.179	11.058	5.557	12.447
-0.250	1.354	13.763	22.595	37.093	12.759	44.610
SeaWiFS						
0.349	-0.436	0.306	0.366	0.438	0.289	0.454
0.249	-0.237	0.502	0.579	0.669	0.479	0.701
0.149	-0.027	0.800	0.941	1.106	0.762	1.174
0.049	0.248	1.409	1.770	2.223	1.310	2.429
-0.050	0.635	3.142	4.320	5.939	2.854	6.712
-0.149	1.187	8.834	15.386	26.798	8.050	34.042

Table 7: Estimated uncertainty ( $\pm 1\sigma$  and empirical 80% confidence intervals) for GLF chlorophyll retrievals. Overbars indicate the averages of the Monte Carlo run values falling in 0.1 bins of  $\log_{10}(MBR)$ .  $Chl_a^{mod}$  is  $10^{(\log_{10}(Chl_a^{mod}))}$  and  $Chl_a^{mod} \pm \sigma$  is  $10^{(\log_{10}(Chl_a^{mod}) \pm \sigma(\log_{10}(Chl_a^{mod})))}$ .

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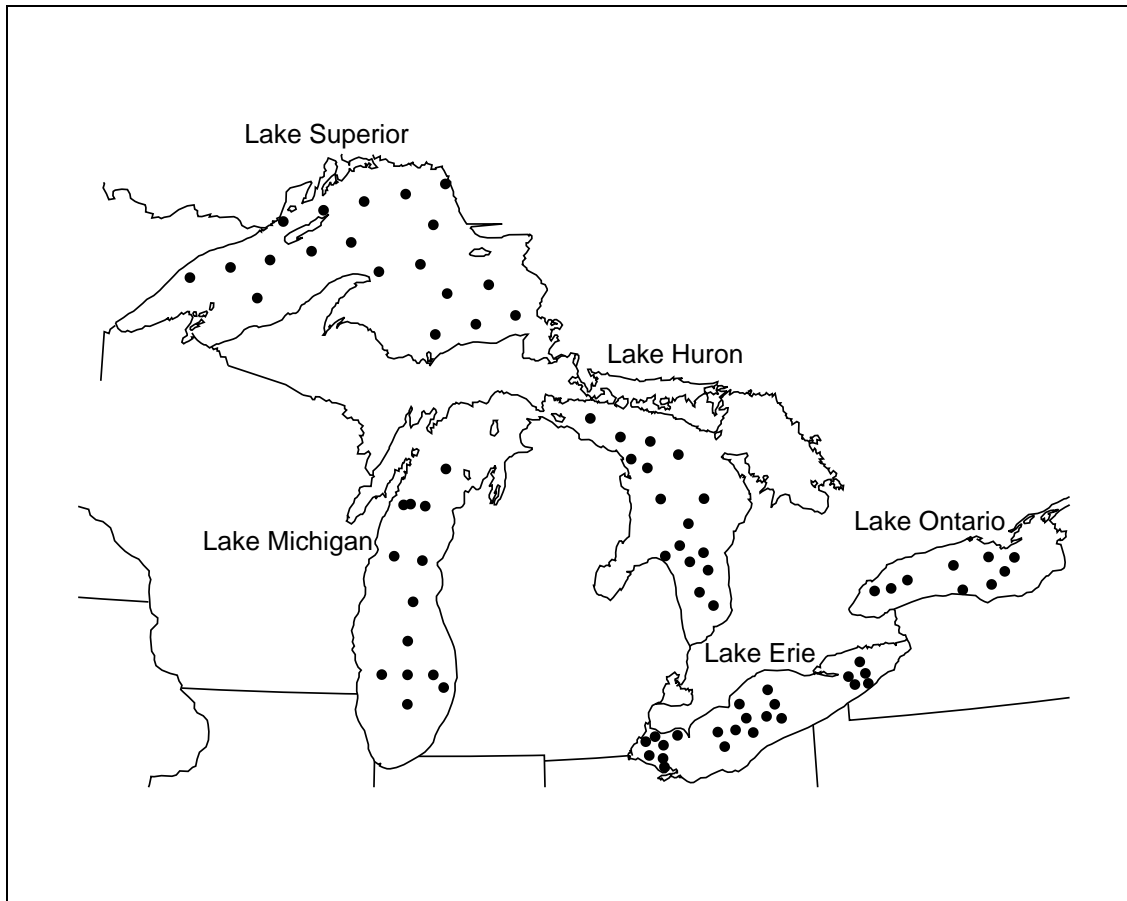


Figure 1: Locations of GLNPO WQS stations.



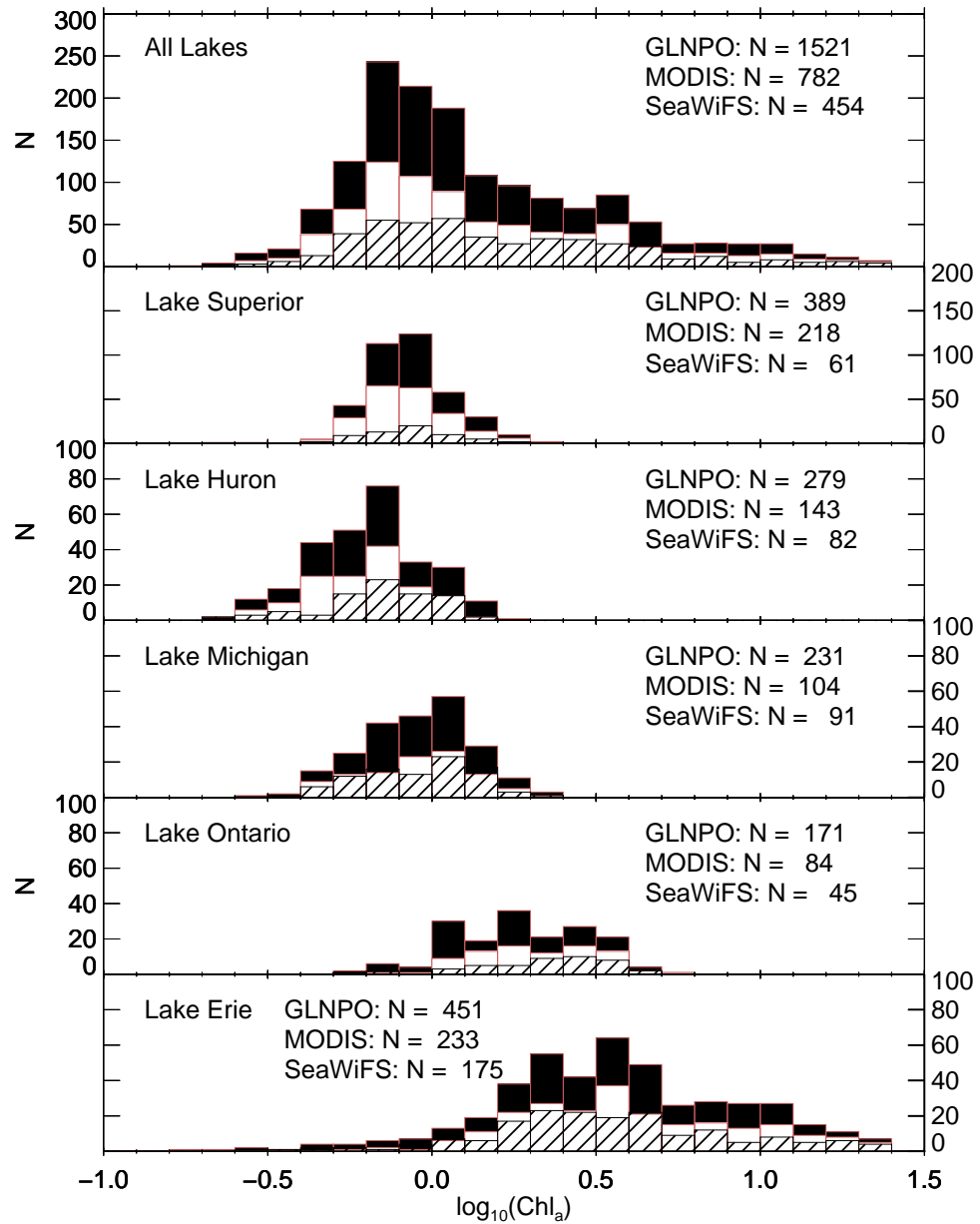


Figure 2: Histograms of GLNPO chlorophyll-a measurements, 2002-2011. Black bars represent the entire set of field data, the white bars represent the field data that were matched with MODIS observations (2002-2011), and the hatched bars represent the field data that were matched with SeaWiFS observations (2002-2010).

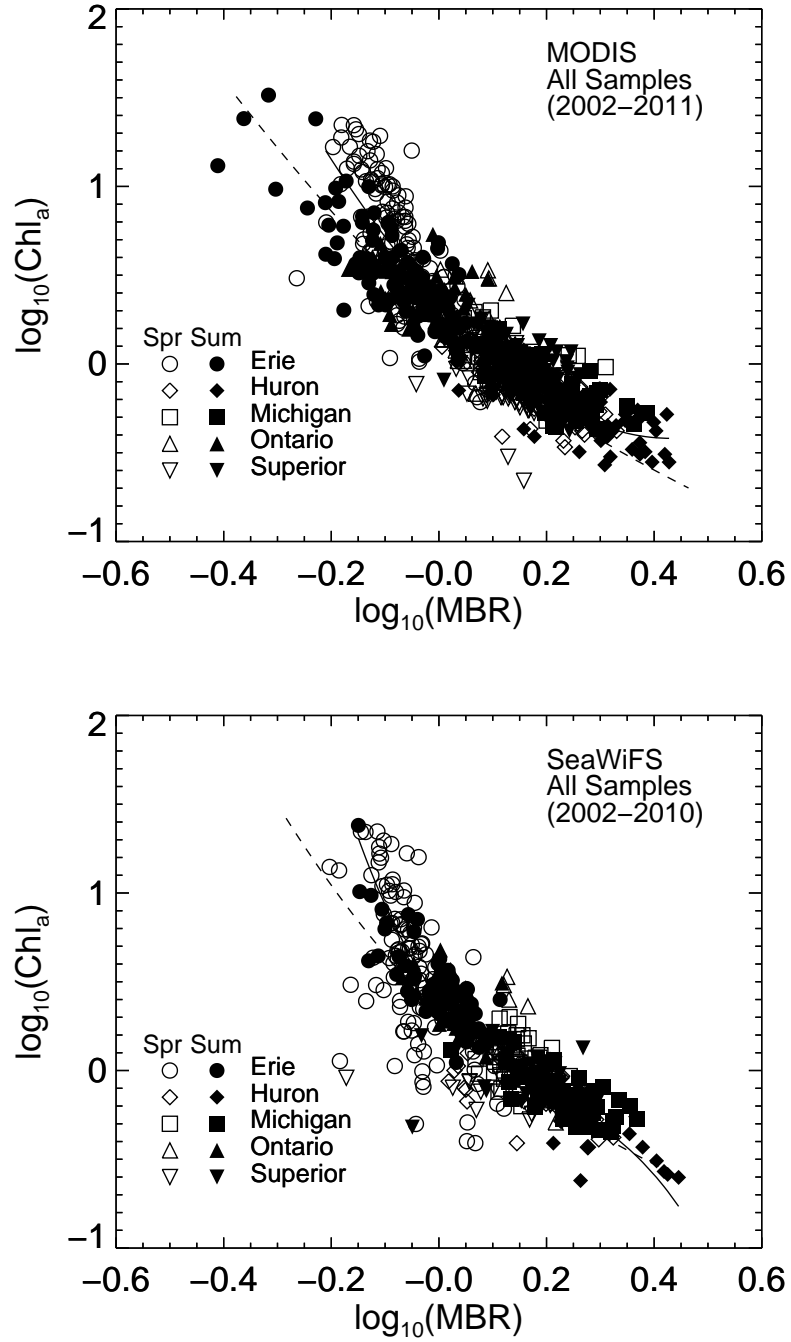


Figure 3:  $\log_{10}(\text{observed chlorophyll})$  vs.  $\log_{10}(\text{maximum band ratio})$  for MODIS (top panel) and SeaWiFS (bottom panel). Dashed lines show the standard NASA algorithms. The GLF model for each set is shown by the solid lines.

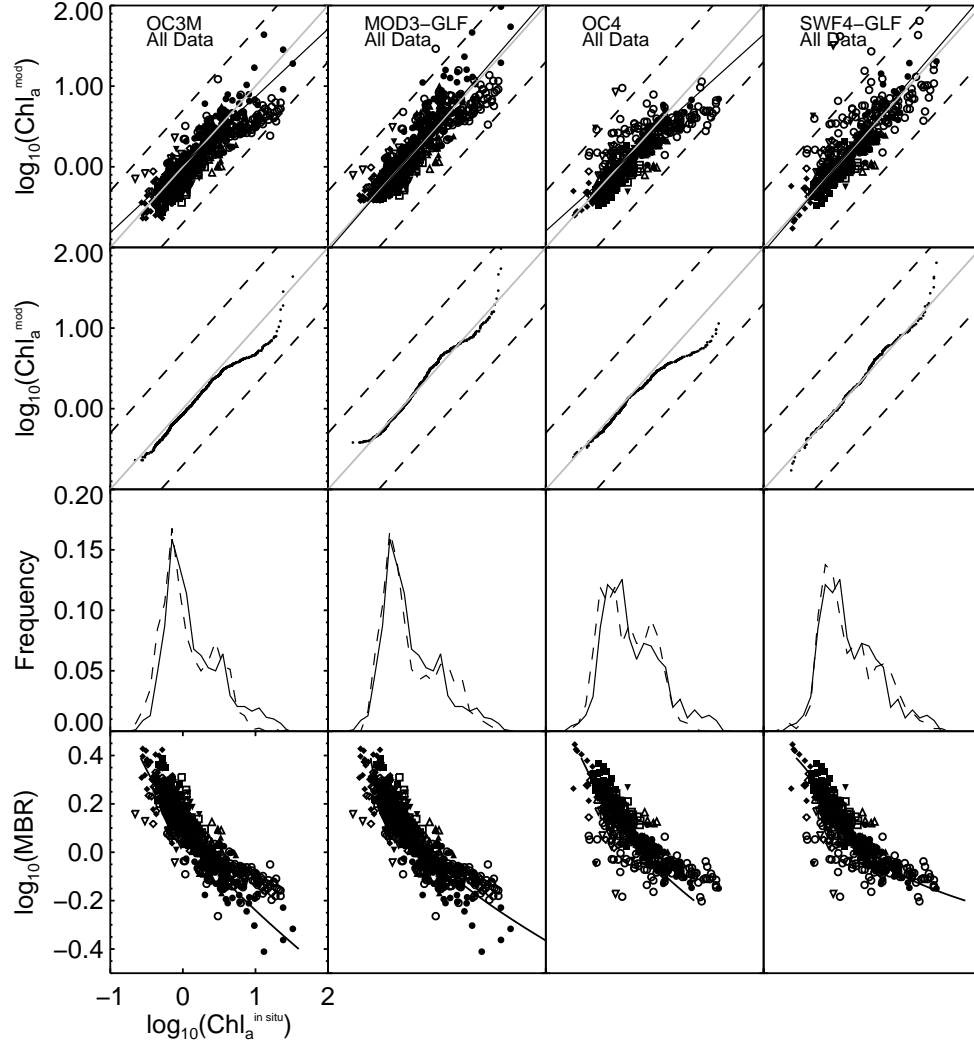


Figure 4: Comparisons between modeled ( $Chl_a^{mod}$ ) and observed chlorophyll ( $Chl_a^{insitu}$ ) data: From top to bottom: Scatterplots (1:1 indicated by gray line, regression indicated by black line); quantile-quantile plots; relative frequency of *in situ* (solid line) and modeled (dashed line) values; maximum band ratio versus *in situ*  $Chl_a$  (symbols) and maximum band ratio (MBR) versus model (curve). Note that the x-axes for each row of figures are shown in column 1. Also shown in the second panel from the top are lines indicating model:*in situ* ratios of 1:5 and 5:1. From left to right columns are NASA OC3Mv6, MODIS GLF, NASA OC4v6, and SeaWiFS GLF.

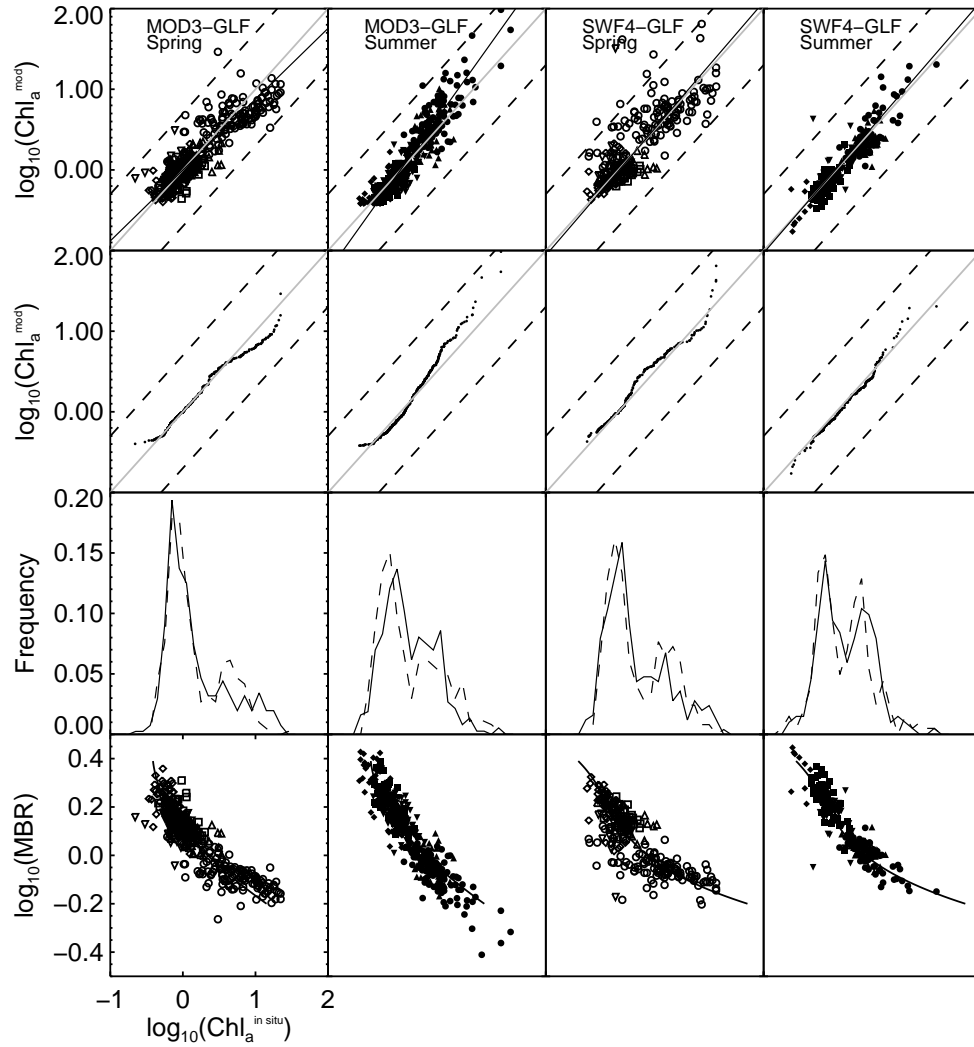


Figure 5: Comparison of GLF modeled ( $Chl_a^{mod}$ ) and observed chlorophyll ( $Chl_a^{in situ}$ ) data by sensor and season. Panels from top to bottom are as described in Fig. 4. From left to right the columns are MODIS GLF spring, MODIS GLF summer, SeaWiFS GLF spring, SeaWiFS GLF summer. Symbols are the same as those used in Fig. 3 and Fig. 4

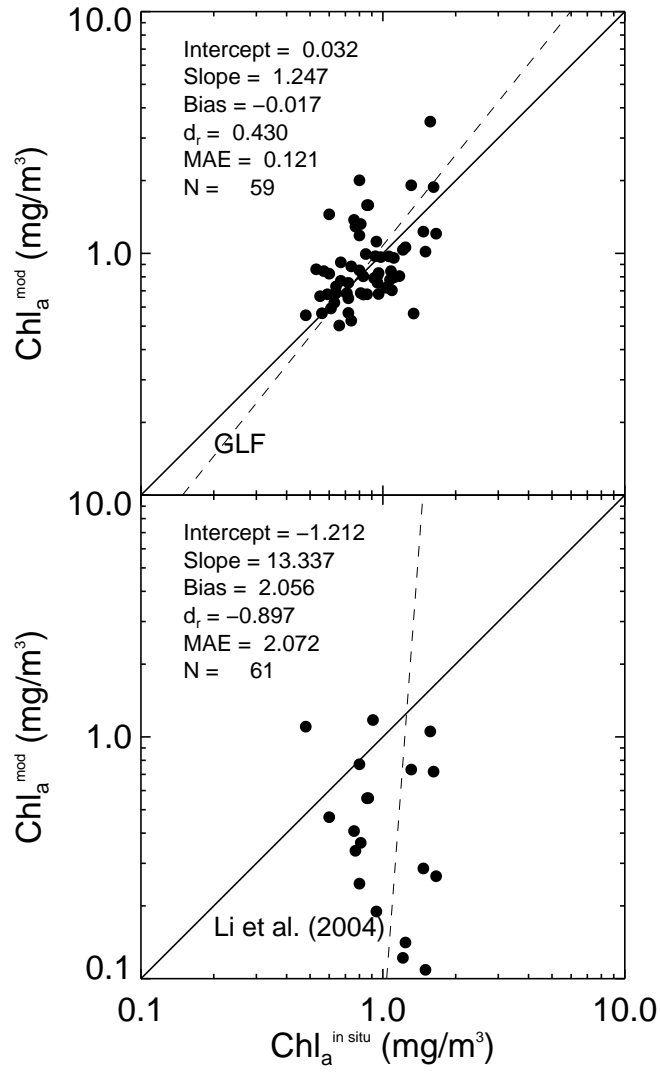


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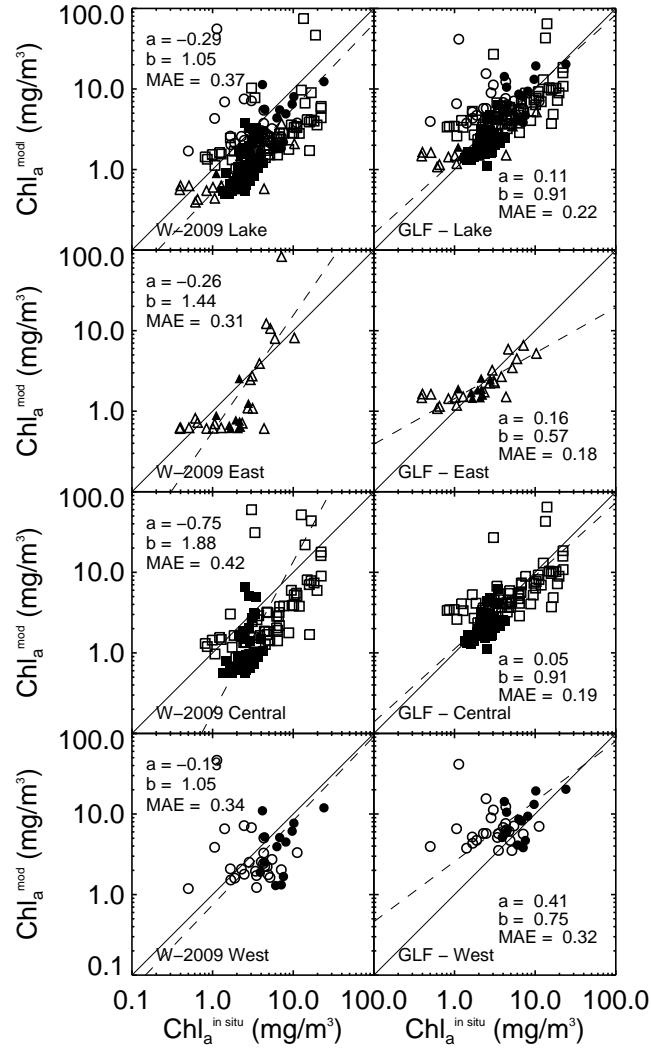


Figure 7: Chlorophyll ( $Chl_a^{mod}$ ) in Lake Erie predicted by the GLF model (right column) and the Witter et al. (2009) whole lake and basin-tuned models (left column) versus observed chlorophyll. Rows are (from top) all Lake Erie stations, eastern basin stations (triangles), central basin stations (squares), and western basin stations (circles). Open symbols represent samples collected in the spring and filled symbols those collected in the summer. Solid line is 1:1 and dashed line is model regression. See methods for explanation of statistics abbreviations.

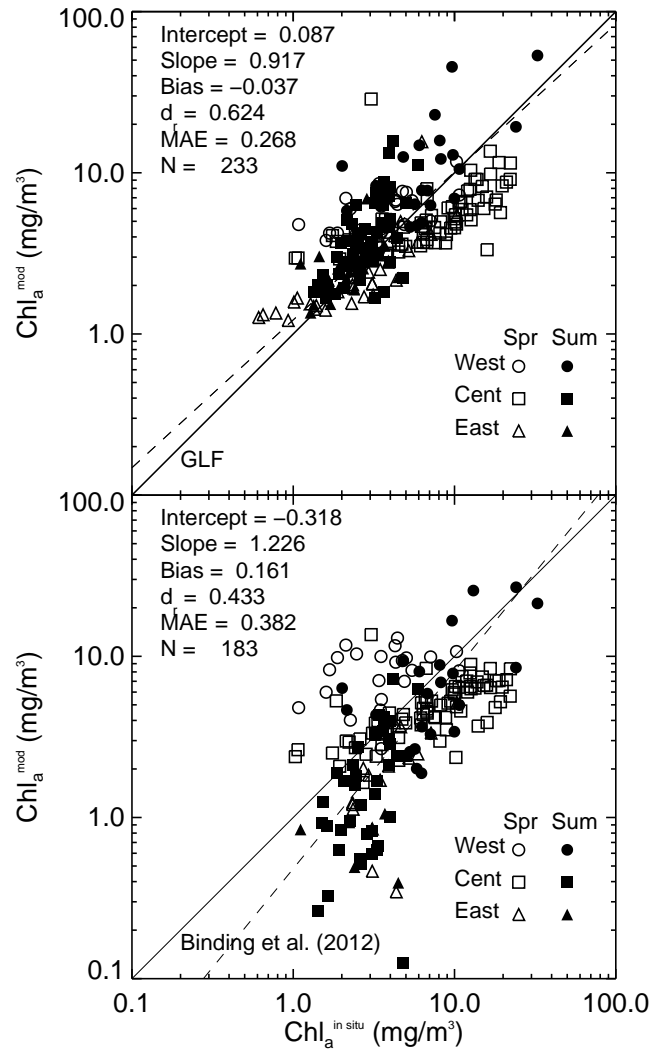


Figure 8: Chlorophyll ( $Chl_a^{mod}$ ) in Lake Erie predicted by the GLF model (top) and the Binding et al. (2012) model (bottom) versus observed chlorophyll ( $Chl_a^{in situ}$ ). Results for the Binding et al. (2012) model were limited to those that produced non-negative values of chlorophyll. Lake Erie basins are designated by symbols (open for spring samples and solid for summer samples). Solid line is 1:1 and dashed line is model regression. See Methods for explanation of abbreviations in legend.

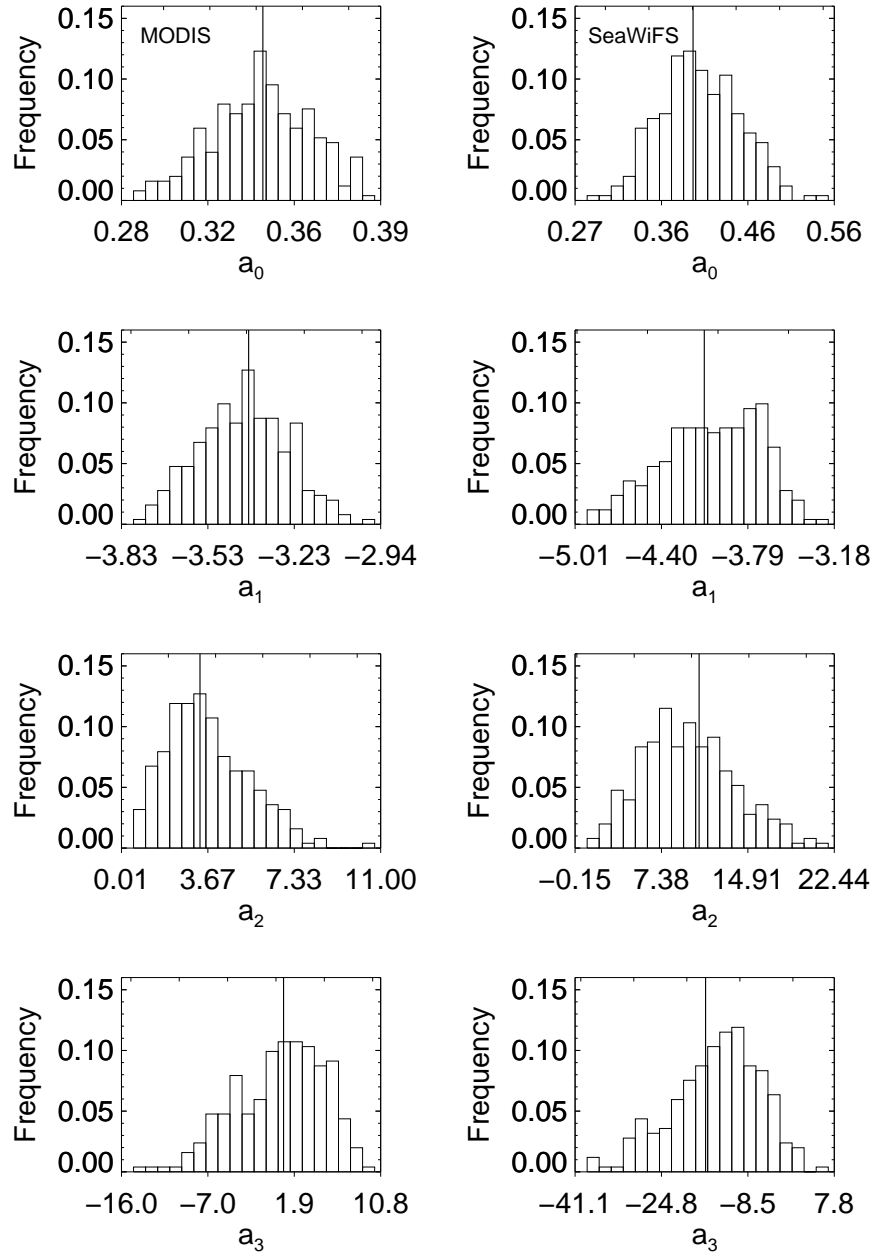


Figure 9: Frequency distributions of GLF model parameters ( $a_0, a_1, a_2, a_3$ ) obtained from five-year subsets of the complete data record. Left column shows results for MODIS, right column for SeaWiFS. Vertical lines indicate parameter values determined from fit to entire dataset.



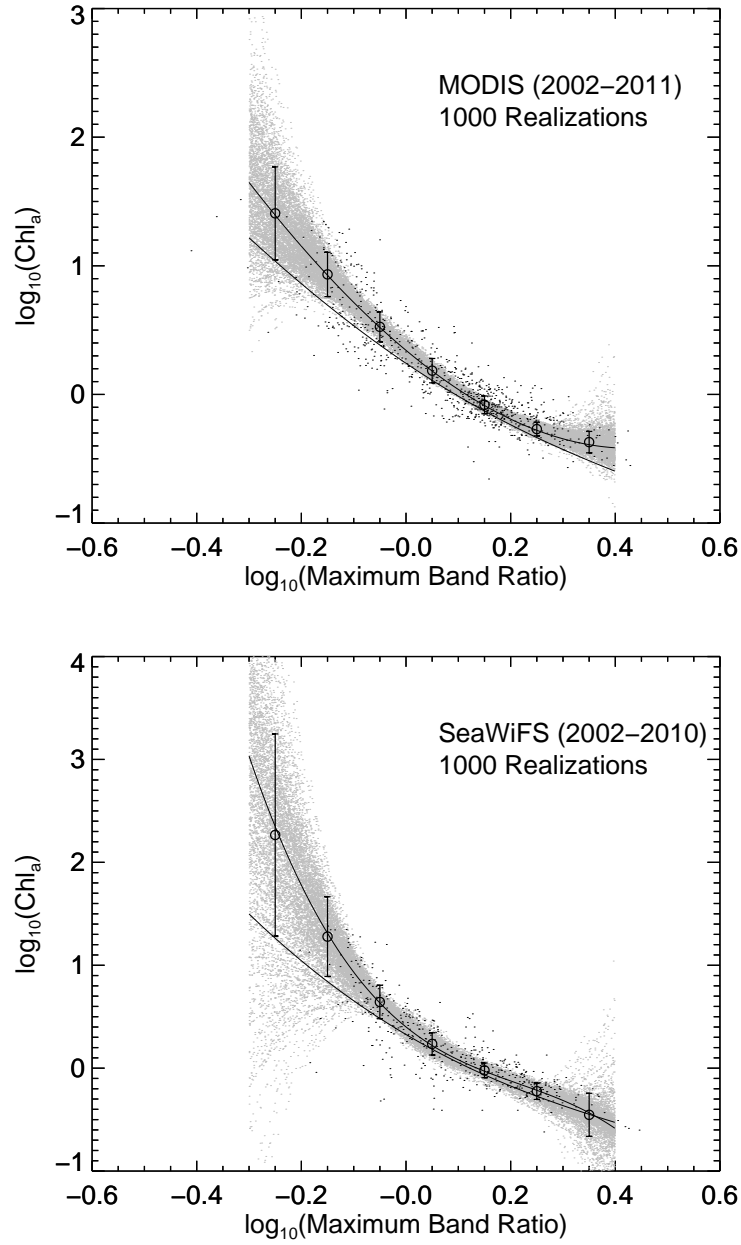


Figure 10: Monte-Carlo (M-C) fits of the 3rd order model (Eq. 2) relating  $\log_{10}(\text{chlorophyll})$  to  $\log_{10}(\text{maximum band ratio})$  for MODIS (top panel) and SeaWiFS (bottom panel). Samples from M-C runs are plotted in gray. The points and error bars show the average  $\pm$  one standard deviation of the samples within 0.1 intervals of  $\log_{10}(\text{maximum band ratio})$ . The upper curve is the GLF model and the lower curve is the standard NASA algorithm.

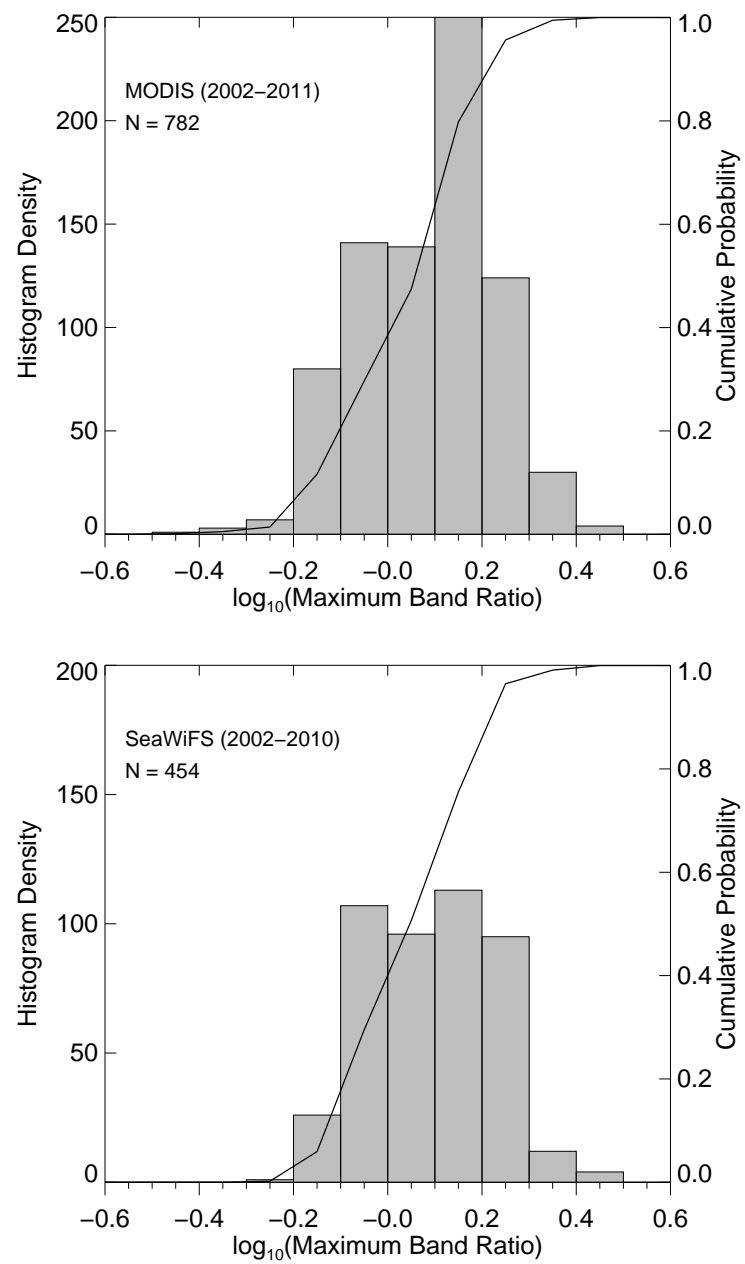


Figure 11: Histograms of  $\log_{10}(\text{maximum band ratio})$  from the MODIS (top panel) and SeaWiFS (bottom panel) observations that were matched with GLNPO field samples.